VE401 RECITATION CLASS NOTE4 Multivariate Random Variables

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1 Definition

Discrete:

Let S be a sample space and Ω a countable subset of \mathbb{R}^n . A discrete multivariate random variable is a map

 $X:S\to \Omega$

together with a function $f_X : \Omega \to \mathbb{R}$ with the properties that

(i)
$$f_X(x) \ge 0$$
 for all $x = (x_1, ..., x_n) \in \Omega$ and

(ii) $\sum_{x \in \Omega} f_X(x) = 1$

Continuous: Let S be a sample space. A continuous multivariate random variable is a map

 $X: S \to \mathbb{R}^n$

together with a function $f_X : \mathbb{R}^n \to \mathbb{R}$ with the properties that

(i)
$$f_X(x) \ge 0$$
 for all $x = (x_1, ..., x_n) \in \mathbb{R}^n$ and

(ii) $\int_{\mathbb{R}^n} f_X(x) dx = 1$

2 Density and Independence

2.1 Marginal Density

$$f_{X_{k}}(x_{k}) = \sum_{x_{1},\dots,x_{k-1},x_{k+1},\dots,x_{n}} f_{\mathbf{X}}(x_{1},\dots,x_{n})$$
$$f_{X_{k}}(x_{k}) = \int_{\mathbb{R}^{n-1}} f_{X}(x) dx_{1}\dots dx_{k-1} dx_{k+1}\dots dx_{n}$$

2.2 Conditional Density

$$f_{X_1|x_2}(x_1) := \frac{f_{X_1X_2}(x_1, x_2)}{f_{X_2}(x_2)} \quad \text{with } f_{X_2}(x_2) > 0$$

2.3 Independence

Two continuous random variables are independent if:

$$f_X(x_1, x_2) = f_{X_1}(x_1) \cdot f_{X_2}(x_2)$$

A full set of n components of a multivariate random variable is independent if:

 $f_X(x_1, ..., x_n) = f_{X_1}(x_1)... \cdot f_{X_n}(x_n)$

Question: Visualization

X and Y are continuous random variables. X takes on values between 0 and 2 while Y takes on values between 0 and 1. Their joint PDF is indicated below in the graph.



Figure 1: The exponential distribution

- 1. Are X and Y independent?
- 2. Find $f_X(x)$ and $f_{Y|X}(y|0.5)$.

Answer: Visualization

1. If X and Y to be independent, any observation of X should not give any information on Y. But in the graph, we see X is observed to be equal to 0, then Y must be 0. You can also describe it mathematically:

$$f_{(X,Y)}(0,0) \neq f_X(0) \cdot f_Y(0)$$

Since $f_{(X,Y)}(0,0) = \frac{1}{2}$, $f_X(0) = 0$, $f_Y(0) = 2$.

You can also think in other ways...

2.

$$f_X(x) = \begin{cases} x/2, & \text{if } 0 \le x \le 1\\ -3x/2 + 3, & \text{if } 1 < x \le 2\\ 0, & \text{otherwise} \end{cases}$$
$$f_{Y|X}(y|0.5) = \begin{cases} 2, & \text{if } 0 \le y \le 1/2\\ 0, & \text{otherwise} \end{cases}$$

3 Expectation

Definition:

$$\mathbf{E}[X] = \begin{pmatrix} \mathbf{E}[X_1] \\ \vdots \\ \mathbf{E}[X_n] \end{pmatrix}$$

$$E[X_k] = \sum_{x_k} x_k f_{X_k}(x_k) = \sum_{x \in \Omega} x_k f_X(x)$$
$$E[X_k] = \int_{\mathbb{R}} x_k f_{X_k}(x_k) dx_k = \int_{\mathbb{R}^n} x_k f_X(x) dx$$

Property:

For a function $\varphi : \mathbb{R}^n \to \mathbb{R}$:

$$\mathbf{E}[\varphi \circ X] = \sum_{x \in \Omega} \varphi(x) f_X(x), \quad \text{or} \quad \mathbf{E}[\varphi \circ X] = \int_{\mathbb{R}^n} \varphi(x) f_X(x) dx$$

4 Variance and Covariance

4.1 Definition

Covariance

$$Cov[X,Y] = E[(X - E[X])(Y - E[Y])] = E[XY] - E[X]E[Y]$$

which comes from:

$$Var[X + Y] = E [((X + Y) - E[X + Y])^{2}]$$

= E [((X - E[X]) + (Y - E[Y]))^{2}]
= E [(X - E[X])^{2} + (Y - E[Y])^{2} + 2(X - E[X])(Y - E[Y])]
= Var[X] + Var[Y] + 2E[(X - E[X])(Y - E[Y])]

Variance

The covariance matrix for a multivariate random variable X is defined as:

$$\operatorname{Var}[X] = \begin{pmatrix} \operatorname{Var}[X_1] & \operatorname{Cov}[X_1, X_2] & \dots & \operatorname{Cov}[X_1, X_n] \\ \operatorname{Cov}[X_1, X_2] & \operatorname{Var}[X_2] & \ddots & \vdots \\ \vdots & \ddots & \ddots & \operatorname{Cov}[X_{n-1}, X_n] \\ \operatorname{Cov}[X_1, X_n] & \dots & \operatorname{Cov}[X_{n-1}, X_n] & \operatorname{Var}[X_n] \end{pmatrix}$$

4.2 Property

- 1. Cov[X,Y] = Cov[Y,X]
- 2. Cov[X,X]=Var[X]
- 3. $\operatorname{Var}[CX] = \operatorname{CVar}[X]C^T$, $C \in \operatorname{Mat}(n \times n; \mathbb{R})$ is a constant matrix with real coefficients.

5 *Discussion: Covariance-Linearity-Independence

Covariance and Independence:

- 1. X and Y are independent $\rightarrow \text{Cov}[X, Y] = 0$.
- 2. $Cov[X, Y] = 0 \Rightarrow X$ and Y are independent.

Therefore, covariance is not a measure of independence.

Then, what does covariance measure?

Covariance and Linearity:

Covariance measures "linearity". In other words, it shows how much is the relationship between X and Y is like the form "Y = a + bX".

Let's first have a mathematical taste of the relationship of covariance and linearity. (You do not need to understand exactly clear now.)

We wish to find a best estimation of the linear relationship between variables X and Y, such that the errors between a + bX and Y are minimized. Also notice hopefully we wish $b \neq 0$

to satisfy this is a "linear relationship". The method we choose is to find such a pair of (a, b) making $e = E[(Y - (a + bX))^2]$ minimized. Since e is a function of a and b:

$$e = E[(Y - (a + bX))^2] = E(Y^2) + b^2 E(X^2) + a^2 - 2bE(XY) + 2abE(X) - 2aE(Y)$$

To make e minimized, we simply make

$$\begin{cases} \frac{\partial e}{\partial a} = 2a + 2bE(X) - 2E(Y) = 0\\ \frac{\partial e}{\partial b} = 2bE(X^2) - 2E(XY) + 2aE(X) = 0 \end{cases}$$

Solve the above equations, we obtain:

$$\begin{cases} b = \frac{Cov[X,Y]}{Var[X]} \\ a = E(Y) - bE[X] \end{cases}$$

Now we notice, when Cov[X, Y] = 0, b = 0; showing X and Y are unlikely to have a linear relationship.

Just relax, let's see a concrete example.

Question: Covariance, Linearity, and Independence

X is a continuous random variable with:

$$f_X(x) = \begin{cases} \frac{1}{2}, & -1 < x < 1\\ 0, & otherwise \end{cases}$$

Let $Y = X^2$. Then:

- 1. What is Cov[X, Y]?
- 2. Are X and Y independent?
- 3. Are X and Y linearly related?

Answer: Covariance, Linearity, and Independence

By definition, $Cov[X, Y] = E[XY] - E[X]E[Y] = E[X^3] - E[X]E[X^2]$ And recall, $E[X^k] := \int_{-\infty}^{\infty} x^k \cdot f_X(x)$ Then it's clear $E[X] = E[X^3] = 0$. Hence:

1. Cov[X, Y] = 0

2. X and Y are dependent

3. X and Y are not linearly related

6 Pearson Correlation Coefficient

Definition

$$\rho_{XY} = \frac{Cov[X,Y]}{\sqrt{Var[X]Var[Y]}}$$

This idea comes from "the covariance of the standardized X and Y". First standardize X and Y to \widetilde{X} and \widetilde{Y} , and Then calculate $Cov[\widetilde{X}, \widetilde{Y}]$.

$$Cov[\widetilde{X}, \widetilde{Y}] = E[\widetilde{X}\widetilde{Y}] - E[\widetilde{X}]E[\widetilde{Y}]$$
$$= \frac{Cov[X, Y]}{\sqrt{Var[X] Var[Y]}}$$

So you can interpret ρ_{XY} as the covariance of the standardized variables, and it is a measure of linearity.

Property

- 1. $-1 \leq \rho_{XY} \leq 1$
- 2. $|\rho_{XY}| = 1$ if and only if there exist numbers $\beta_0, \beta_1 \in \mathbb{R}, \beta_1 \neq 0$, such that almost surely $Y = \beta_0 + \beta_1 X$.
- 3. Further $\rho_{XY} = 1$ leads to almost surely $\widetilde{X} \widetilde{Y} = 0$, and $\rho_{XY} = -1$ leads to almost surely $\widetilde{X} + \widetilde{Y} = 0$.

6.1 Fisher Transformation

 $Var[\widetilde{X} - \widetilde{Y}] = 2 - 2\rho_{XY}$, and $Var[\widetilde{X} + \widetilde{Y}] = 2 + 2\rho_{XY}$. The Fisher transformation is defined as:

$$\ln(\sqrt{\frac{\operatorname{Var}[\tilde{X}+\tilde{Y}]}{\operatorname{Var}[\tilde{X}-\tilde{Y}]}}) = \frac{1}{2}\ln\left(\frac{1+\rho_{XY}}{1-\rho_{XY}}\right) = \operatorname{Artanh}\left(\rho_{XY}\right) \in \mathbb{R}$$

Then we also have:

$$\rho_{XY} = \tanh\left(\ln\left(\frac{\sigma_{\widetilde{X}+\widetilde{Y}}}{\sigma_{\widetilde{X}-\widetilde{Y}}}\right)\right)$$

6.2 ρ_{XY} and Linearity

- 1. The closer $|\rho_{XY}|$ is to 1, the more likely X and Y have a linear relationship.
- 2. <u>Positive correlation</u>: $\rho_{XY} > 0$, $Var[\tilde{X} \tilde{Y}] < Var[\tilde{X} + \tilde{Y}]$. X and Y tend to be more like $\tilde{X} = \tilde{Y}$, in other words, more positively related. When X is larger, then Y is likely to be larger.
- 3. Negative correlation: $\rho_{XY} < 0$, X and Y tend to be more like $\tilde{X} = -\tilde{Y}$. When X is larger, then Y is likely to be smaller.



Figure 2: The Pearson Correlation Coefficient

6.3 Bivariate Normal Distribution

X and Y should each follow a normal distribution, but may be not independent. Then the joint density function is:

$$f_{XY}(x,y) = \frac{1}{2\pi\sigma_X\sigma_Y\sqrt{1-\varrho^2}} e^{-\frac{1}{2(1-\varrho^2)}\left[\left(\frac{x-\mu_X}{\sigma_X}\right)^2 - 2\varrho\left(\frac{x-\mu_X}{\sigma_X}\right)\left(\frac{y-\mu_Y}{\sigma_Y}\right) + \left(\frac{y-\mu_Y}{\sigma_Y}\right)^2\right]}$$

Property:

- 1. $-1 < \rho < 1, \rho = \rho_{XY}$
- 2. $\mu_X = E[X], \, \delta_X^2 = Var[X]$. Same for Y.
- 3. $\rho = 0 \iff X$ and Y are independent. (Notice this is special.)

7 Hypergeometric Distribution

Interpretation:

A total of N balls, r red and N - r black. Draw n balls out without putting back. Assume r > n and N - r > n. The random variable X describes the number of red balls in the n drawn balls.

Comment:

It is a sequence of identical but not independent Bernoulli trials. Each draw is a Bernoulli trial with $p = \frac{r}{N}$.

Features:

1. N, r, n are the parameters

2.
$$f_X(x) = \frac{\binom{r}{x}\binom{N-r}{n-x}}{\binom{N}{n}}$$

- 3. $E[X] = n \frac{r}{N}$
- 4. Var $X = n \frac{r}{N} \frac{N-r}{N} \frac{N-n}{N-1}$

Approximate Hypergeometric with Binomial:

Recall for a Binomial distribution, E[X] = np, Var X = npq.

If the sampling fraction $\frac{n}{N}$ is small (less than 0.05), we can use $E[X] = n\frac{r}{N} = p$, $n\frac{N-r}{N} = q$ to estimate the Hypergeometric distribution with a Binomial distribution.

We can interpret as: when the sample size n is small, it does not affect the left balls much. So, the trials are approximately independent.

Question: Covariance and Hypergeometric

There are totally N balls, r red and N-r black. We draw 2 balls out one by one without putting back. And we define three Bernoulli random variables representing the below events:

 X_1 : Red ball at the first draw.

 X_2 : Red ball at the second draw.

 X_3 : Black ball at the second draw.

Then, what is $Cov[X_1, X_2]$, and what is $Cov[X_1, X_3]$?

And, what is $\rho_{X_1X_2}$, and what is $\rho_{X_1X_3}$?

Answer: Covariance and Hypergeometric

We have calculated $\operatorname{Cov}[X_1, X_2]$ in class. $\operatorname{Cov}[X_1, X_2] = \operatorname{E}[X_1X_2] - \operatorname{E}[X_1]\operatorname{E}[X_2] = -\frac{1}{N}\frac{r(N-r)}{N(N-1)} < 0.$ Similarly since X_1X_3 is still a Bernoulli trial, hence $\operatorname{E}[X_1X_3] = \operatorname{P}[X_1 = 1 \text{ and } X_3 = 1] = \frac{r}{N}\frac{N-r}{N-1}.$ Then $\operatorname{Cov}[X_1, X_3] = \operatorname{E}[X_1X_2] - \operatorname{E}[X_1]\operatorname{E}[X_2] = \frac{1}{N}\frac{r(N-r)}{N(N-1)} > 0.$ Further with $\operatorname{Var}[X_1] = \operatorname{Var}[X_2] = \frac{r}{N}(1-\frac{r}{N})$ and $\operatorname{Var}[X_3] = \frac{N-r}{N}(1-\frac{N-r}{N}).$ We obtain: $\rho_{X_1X_2} = -\frac{1}{N-1} < 0$, negative correlated. $\rho_{X_1X_3} = \frac{1}{N-1} > 0$, positive correlated. This also help you understand the positive and negative ρ_{XY} better. 1. When $X_1 = 1, X_2$ is more likely to be 0, and X_3 is more likely to be 1.

2. When N becomes larger, $|\rho_{X_1X_2}|$ and $|\rho_{X_1X_3}|$ become smaller. So the effect of X_1 on X_2 and X_3 becomes less. When N is large enough, ρ is close to 0, and we estimate the two trials as independent.